6/29/2020

First connection of RPi and Matek board

* Followed Ardupilot instructions <https://ardupilot.org/dev/docs/raspberry-pi-via-mavlink.html>
  + Wiring was snipped duponts (female end goes over Pi headers, snipped end soldered to Matek
  + This is sloppy, must be a better way
* Python3 mavproxy.py command wont work, just use mavproxy.py
* Mavproxy.py with manually set baud rate 921600 results in “link 1 down”
  + Just don’t specify baud rate, it will work
* Ran sample dronekit script, connected, printed some parameters, and closed
* Needed to set baud rate on connect() call to 57600
  + Without explicit baud rate set, got timeout error